

Data Mining:

Concepts and Techniques

— Chapter 4 —

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Chapter 4. Classification and Prediction

- What is classification? What is prediction? 
- Issues regarding classification and prediction
- Classification by decision tree induction
- Bayesian classification
- Rule-based classification
- Associative classification
- Lazy learners (or learning from your neighbors)
- Other classification methods
- Prediction
- Summary

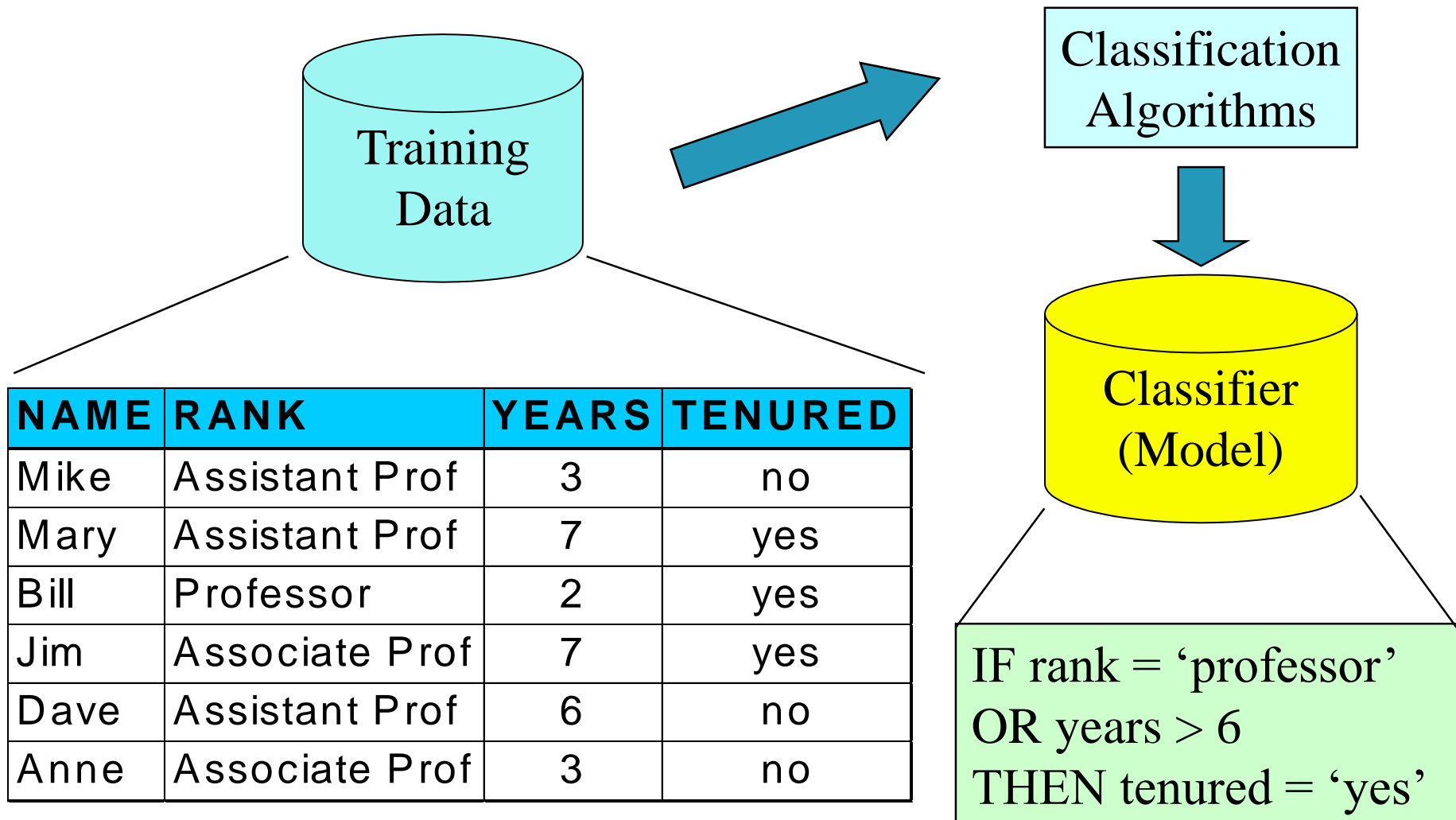
Classification vs. Prediction

- **Classification**
 - predicts categorical class labels (discrete or nominal)
 - classifies data (constructs a model) based on the training set and the values (**class labels**) in a classifying attribute and uses it in classifying new data
- **Prediction**
 - models continuous-valued functions, i.e., predicts unknown or missing values
- Typical applications
 - **Covid-19 new cases and deaths**
 - Target marketing
 - Medical diagnosis
 - Fraud detection

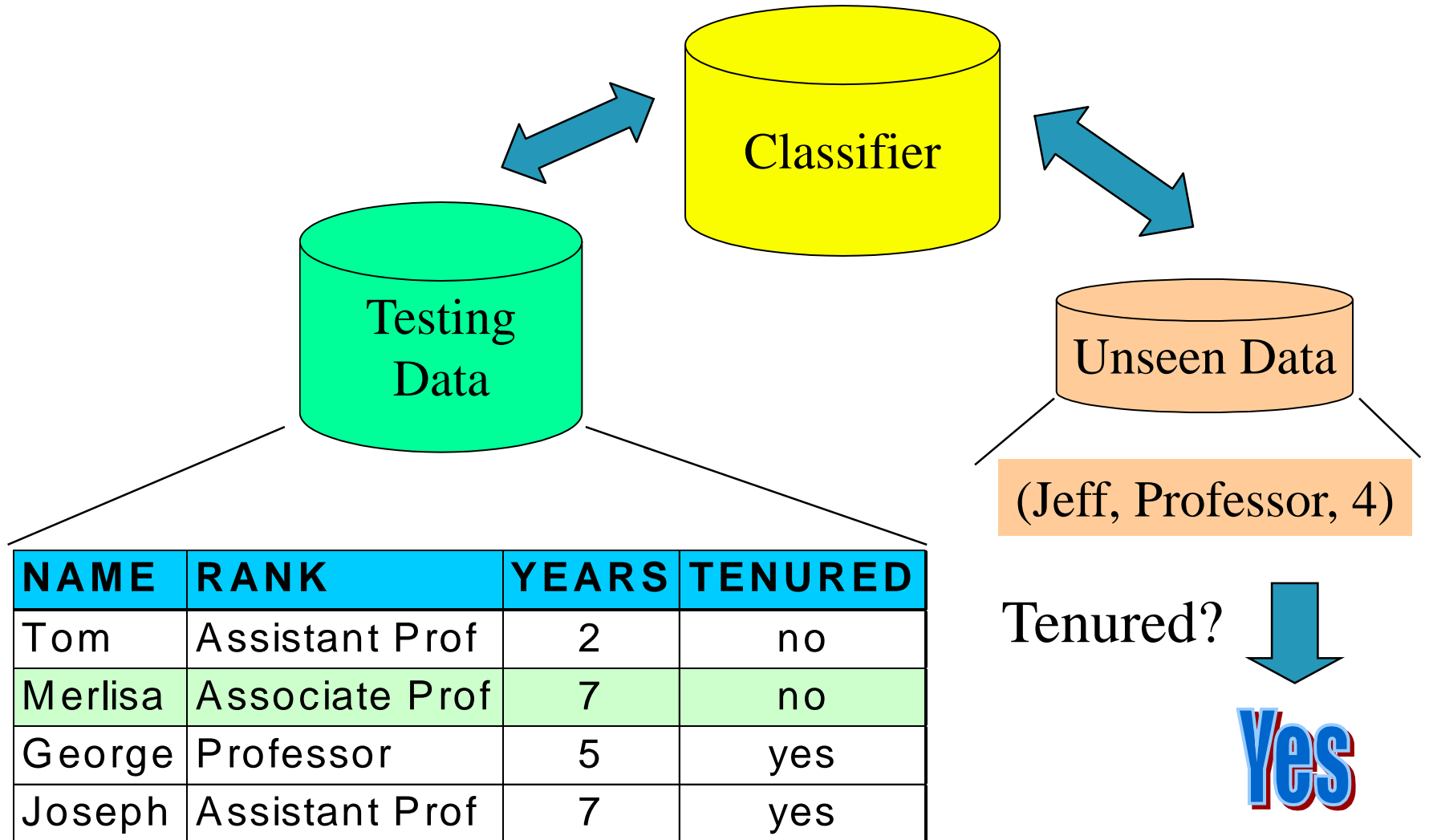
Classification—A Two-Step Process

- **Model construction**: describing a set of predetermined classes
 - Each tuple/sample is assumed to belong to a predefined class, as determined by the **class label attribute**
 - The set of tuples used for model construction is **training set**
 - The model is represented as classification rules, decision trees, or mathematical formulae
- **Model usage**: for classifying future or unknown objects
 - **Estimate accuracy** of the model
 - The known label of test sample is compared with the classified result from the model
 - Accuracy rate is the percentage of test set samples that are correctly classified by the model
 - Test set is independent of training set, otherwise over-fitting will occur
 - If the accuracy is acceptable, use the model to **classify data** tuples whose class labels are not known

Process (1): Model Construction




Process (2): Using the Model in Prediction



Supervised vs. Unsupervised Learning

- **Supervised learning (classification)**
 - Supervision: The training data (observations, measurements, etc.) are accompanied by labels indicating the class of the observations
 - New data is classified based on the training set
- **Unsupervised learning (clustering)**
 - The class labels of training data is unknown
 - Given a set of measurements, observations, etc. with the aim of establishing the existence of classes or clusters in the data

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Issues: Data Preparation

- Data cleaning
 - Preprocess data in order to reduce noise and handle missing values
- Relevance analysis (feature selection)
 - Remove the irrelevant or redundant attributes
- Data transformation
 - Generalize and/or normalize data

Issues: Evaluating Classification Methods

- Accuracy
 - classifier accuracy: predicting class label
 - predictor accuracy: guessing value of predicted attributes
- Speed
 - time to construct the model (training time)
 - time to use the model (classification/prediction time)
- Robustness: handling noise and missing values
- Scalability: efficiency in disk-resident databases
- Interpretability
 - understanding and insight provided by the model
- Other measures, e.g., goodness of rules, such as decision tree size or compactness of classification rules

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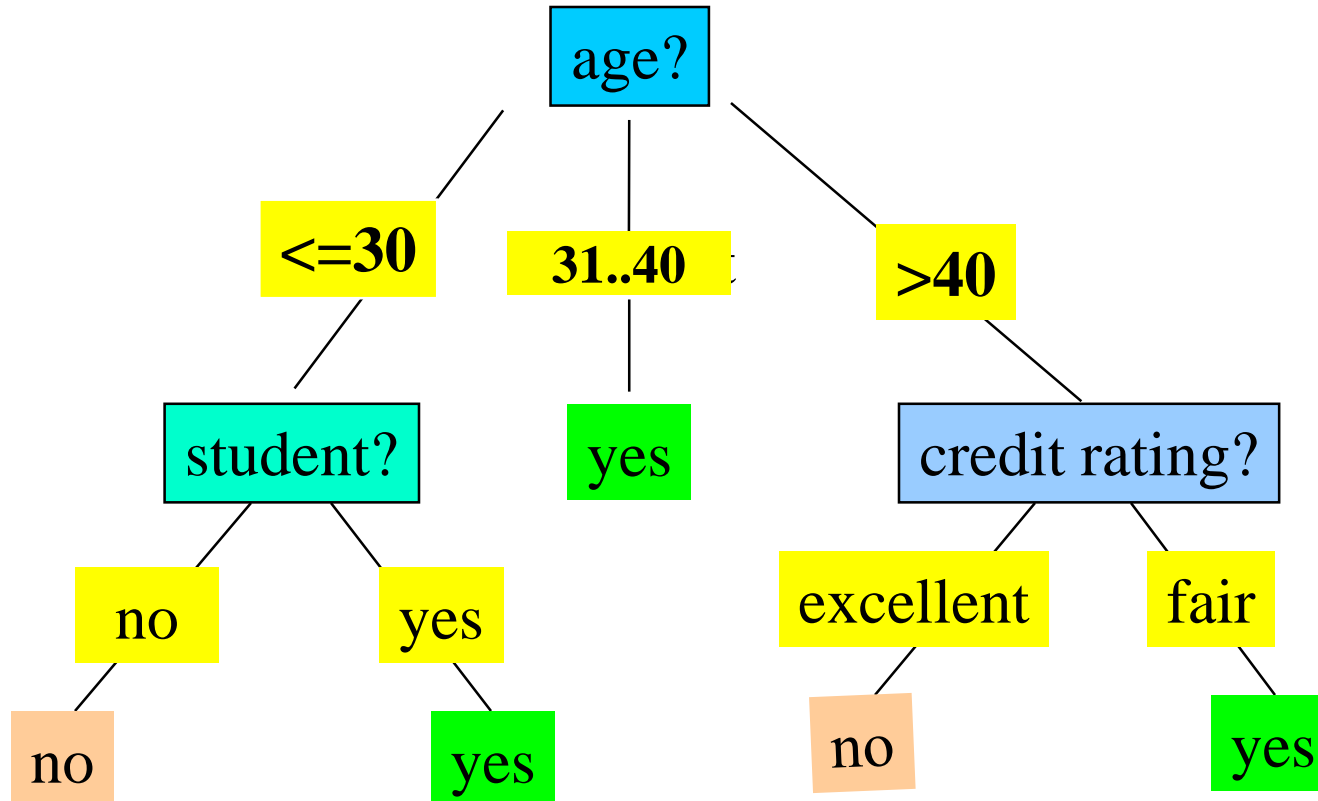
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Decision Tree Induction: Training Dataset

This follows an example of Quinlan's ID3 (Playing Tennis)

age	income	student	credit_rating	buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
31...40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31...40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31...40	medium	no	excellent	yes
31...40	high	yes	fair	yes
>40	medium	no	excellent	no

Output: A Decision Tree for "*buys_computer*"



Algorithm for Decision Tree Induction

- Basic algorithm (a greedy algorithm)
 - Tree is constructed in a **top-down recursive divide-and-conquer manner**
 - At start, all the training examples are at the root
 - Attributes are categorical (if continuous-valued, they are discretized in advance)
 - Examples are partitioned recursively based on selected attributes
 - Test attributes are selected on the basis of a heuristic or statistical measure (e.g., **information gain**)
- Conditions for stopping partitioning
 - All samples for a given node belong to the same class
 - There are no remaining attributes for further partitioning – **majority voting** is employed for classifying the leaf
 - There are no samples left

Attribute Selection Measure: Information Gain (ID3/C4.5)

- Select the attribute with the highest information gain
- Let p_i be the probability that an arbitrary tuple in D belongs to class C_i , estimated by $|C_{i,D}|/|D|$
- **Expected information** (entropy) needed to classify a tuple in D :

$$Info(D) = -\sum_{i=1}^m p_i \log_2(p_i)$$

- **Information** needed (after using A to split D into v partitions) to classify D :

$$Info_A(D) = \sum_{j=1}^v \frac{|D_j|}{|D|} \times I(D_j)$$

- **Information gained** by branching on attribute A

$$Gain(A) = Info(D) - Info_A(D)$$

Attribute Selection: Information Gain

- Class P: buys_computer = "yes"
- Class N: buys_computer = "no"

$$Info(D) = I(9,5) = -\frac{9}{14} \log_2\left(\frac{9}{14}\right) - \frac{5}{14} \log_2\left(\frac{5}{14}\right) = 0.940$$

$$Info_{age}(D) = \frac{5}{14} I(2,3) + \frac{4}{14} I(4,0) + \frac{5}{14} I(3,2) = 0.694$$

age	p_i	n_i	$I(p_i, n_i)$
≤ 30	2	3	0.971
31...40	4	0	0
> 40	3	2	0.971

$\frac{5}{14} I(2,3)$ means "age ≤ 30 " has 5 out of 14 samples, with 2 yes'es and 3 no's. Hence

$$Gain(age) = Info(D) - Info_{age}(D) = 0.246$$

Similarly,

$$Gain(income) = 0.029$$

$$Gain(student) = 0.151$$

$$Gain(credit_rating) = 0.048$$

age	income	student	credit_rating	buys_computer
≤ 30	high	no	fair	no
≤ 30	high	no	excellent	no
31...40	high	no	fair	yes
> 40	medium	no	fair	yes
> 40	low	yes	fair	yes
> 40	low	yes	excellent	no
31...40	low	yes	excellent	yes
≤ 30	medium	no	fair	no
≤ 30	low	yes	fair	yes
> 40	medium	yes	fair	yes
≤ 30	medium	yes	excellent	yes
31...40	medium	no	excellent	yes
31...40	high	yes	fair	yes
> 40	medium	no	excellent	no

Gain Ratio for Attribute Selection (C4.5)

- Information gain measure is biased towards attributes with a large number of values
- C4.5 (a successor of ID3) uses gain ratio to overcome the problem (normalization to information gain)

$$\text{SplitInfo}_A(D) = -\sum_{j=1}^v \frac{|D_j|}{|D|} \times \log_2\left(\frac{|D_j|}{|D|}\right)$$

- $\text{GainRatio}(A) = \text{Gain}(A)/\text{SplitInfo}(A)$
- Ex. $\text{SplitInfo}_A(D) = -\frac{4}{14} \times \log_2\left(\frac{4}{14}\right) - \frac{6}{14} \times \log_2\left(\frac{6}{14}\right) - \frac{4}{14} \times \log_2\left(\frac{4}{14}\right) = 0.926$
 - $\text{gain_ratio}(\text{income}) = 0.029/0.926 = 0.031$
- The attribute with the maximum gain ratio is selected as the splitting attribute

Gini index (CART, IBM IntelligentMiner)

- If a data set D contains examples from n classes, gini index, $gini(D)$ is defined as

$$gini(D) = 1 - \sum_{j=1}^n p_j^2$$

where p_j is the relative frequency of class j in D

- If a data set D is split on A into two subsets D_1 and D_2 , the $gini$ index $gini_A(D)$ is defined as

$$gini_A(D) = \frac{|D_1|}{|D|} gini(D_1) + \frac{|D_2|}{|D|} gini(D_2)$$

- Reduction in Impurity:

$$\Delta gini(A) = gini(D) - gini_A(D)$$

- The attribute provides the smallest $gini_{split}(D)$ (or the largest reduction in impurity) is chosen to split the node (*need to enumerate all the possible splitting points for each attribute*)

Gini index (CART, IBM IntelligentMiner)

- Ex. D has 9 tuples in `buys_computer = "yes"` and 5 in "no"

$$gini(D) = 1 - \left(\frac{9}{14}\right)^2 - \left(\frac{5}{14}\right)^2 = 0.459$$

- Suppose the attribute `income` partitions D into 10 in D_1 : {low, medium} and 4 in D_2

$$\begin{aligned} gini_{income \in \{low, medium\}}(D) &= \left(\frac{10}{14}\right) Gini(D_1) + \left(\frac{4}{14}\right) Gini(D_2) \\ &= \frac{10}{14} \left(1 - \left(\frac{6}{10}\right)^2 - \left(\frac{4}{10}\right)^2\right) + \frac{4}{14} \left(1 - \left(\frac{1}{4}\right)^2 - \left(\frac{3}{4}\right)^2\right) \\ &= 0.450 \\ &= Gini_{income \in \{high\}}(D) \end{aligned}$$

but $gini_{\{medium, high\}}$ is 0.30 and thus the best since it is the lowest

- All attributes are assumed continuous-valued
- May need other tools, e.g., clustering, to get the possible split values
- Can be modified for categorical attributes

Comparing Attribute Selection Measures

- The three measures, in general, return good results but
 - Information gain:
 - biased towards multivalued attributes
 - Gain ratio:
 - tends to prefer unbalanced splits in which one partition is much smaller than the others
 - Gini index:
 - biased to multivalued attributes
 - has difficulty when # of classes is large
 - tends to favor tests that result in equal-sized partitions and purity in both partitions

Other Attribute Selection Measures

- CHAID: a popular decision tree algorithm, measure based on χ^2 test for independence
- C-SEP: performs better than info. gain and gini index in certain cases
- G-statistics: has a close approximation to χ^2 distribution
- MDL (Minimal Description Length) principle (i.e., the simplest solution is preferred):
 - The best tree as the one that requires the fewest # of bits to both (1) encode the tree, and (2) encode the exceptions to the tree
- Multivariate splits (partition based on multiple variable combinations)
 - CART: finds multivariate splits based on a linear comb. of attrs.
- Which attribute selection measure is the best?
 - Most give good results, none is significantly superior than others

Overfitting and Tree Pruning

- Overfitting: An induced tree may overfit the training data
 - Too many branches, some may reflect anomalies due to noise or outliers
 - Poor accuracy for unseen samples
- Two approaches to avoid overfitting
 - Prepruning: Halt tree construction early—do not split a node if this would result in the goodness measure falling below a threshold
 - Difficult to choose an appropriate threshold
 - Postpruning: Remove branches from a “fully grown” tree—get a sequence of progressively pruned trees
 - Use a set of data different from the training data to decide which is the “best pruned tree”

Enhancements to Basic Decision Tree Induction

- Allow for continuous-valued attributes
 - Dynamically define new discrete-valued attributes that partition the continuous attribute value into a discrete set of intervals
- Handle missing attribute values
 - Assign the most common value of the attribute
 - Assign probability to each of the possible values
- Attribute construction
 - Create new attributes based on existing ones that are sparsely represented
 - This reduces fragmentation, repetition, and replication

Classification in Large Databases

- Classification—a classical problem extensively studied by statisticians and machine learning researchers
- Scalability: Classifying data sets with millions of examples and hundreds of attributes with reasonable speed
- Why decision tree induction in data mining?
 - relatively faster learning speed (than other classification methods)
 - convertible to simple and easy to understand classification rules
 - can use SQL queries for accessing databases
 - comparable classification accuracy with other methods

Scalable Decision Tree Induction Methods

- **SLIQ** (EDBT'96 — Mehta et al.)
 - Builds an index for each attribute and only class list and the current attribute list reside in memory
- **SPRINT** (VLDB'96 — J. Shafer et al.)
 - Constructs an attribute list data structure
- **PUBLIC** (VLDB'98 — Rastogi & Shim)
 - Integrates tree splitting and tree pruning: stop growing the tree earlier
- **RainForest** (VLDB'98 — Gehrke, Ramakrishnan & Ganti)
 - Builds an AVC-list (attribute, value, class label)
- **BOAT** (PODS'99 — Gehrke, Ganti, Ramakrishnan & Loh)
 - Uses bootstrapping to create several small samples

Scalability Framework for RainForest

- Separates the scalability aspects from the criteria that determine the quality of the tree
- Builds an AVC-list: **AVC (Attribute, Value, Class_label)**
- **AVC-set** (of an attribute X)
 - Projection of training dataset onto the attribute X and class label where counts of individual class label are aggregated
- **AVC-group** (of a node n)
 - Set of AVC-sets of all predictor attributes at the node n

Rainforest: Training Set and Its AVC Sets

Training Examples

age	income	student	credit_rating	comp
<=30	high	no	fair	no
<=30	high	no	excellent	no
31...40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31...40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31...40	medium	no	excellent	yes
31...40	high	yes	fair	yes
>40	medium	no	excellent	no

AVC-set on *Age*

Age	Buy_Computer	
	yes	no
<=30	3	2
31..40	4	0
>40	3	2

AVC-set on *income*

income	Buy_Computer	
	yes	no
high	2	2
medium	4	2
low	3	1

AVC-set on *Student*

student	Buy_Computer	
	yes	no
yes	6	1
no	3	4


AVC-set on *credit_rating*

Credit rating	Buy_Computer	
	yes	no
fair	6	2
excellent	3	3

BOAT (Bootstrapped Optimistic Algorithm for Tree Construction)

- Use a statistical technique called *bootstrapping* to create several smaller samples (subsets), each fits in memory
- Each subset is used to create a tree, resulting in several trees
- These trees are examined and used to construct a new tree T'
 - It turns out that T' is very close to the tree that would be generated using the whole data set together
- Adv: requires only two scans of DB, an incremental alg.

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Bayesian Classification: Why?

- A statistical classifier: performs *probabilistic prediction*, *i.e.*, predicts class membership probabilities
- Foundation: Based on Bayes' Theorem.
- Performance: A simple Bayesian classifier, *naïve Bayesian classifier*, has comparable performance with decision tree and selected neural network classifiers
- Incremental: Each training example can incrementally increase/decrease the probability that a hypothesis is correct — prior knowledge can be combined with observed data
- Standard: Even when Bayesian methods are computationally intractable, they can provide a standard of optimal decision making against which other methods can be measured

Bayesian Theorem: Basics

- Let \mathbf{X} be a data sample ("*evidence*"): class label is unknown
- Let H be a *hypothesis* that X belongs to class C
- Classification is to determine $P(H|\mathbf{X})$, the probability that the hypothesis holds given the observed data sample \mathbf{X}
- $P(H)$ (*prior probability*), the initial probability
 - E.g., \mathbf{X} will buy computer, regardless of age, income, ...
- $P(\mathbf{X})$: probability that sample data is observed
- $P(\mathbf{X}|H)$ (*posteriori probability*), the probability of observing the sample \mathbf{X} , given that the hypothesis holds
 - E.g., Given that \mathbf{X} will buy computer, the prob. that X is 31..40, medium income

Bayesian Theorem

- Given training data \mathbf{X} , *posteriori probability of a hypothesis* H , $P(H|\mathbf{X})$, follows the Bayes theorem

$$P(H | \mathbf{X}) = \frac{P(\mathbf{X} | H)P(H)}{P(\mathbf{X})}$$

- Informally, this can be written as
posteriori = likelihood x prior/evidence
- Predicts \mathbf{X} belongs to C_i iff the probability $P(C_i|\mathbf{X})$ is the highest among all the $P(C_k|\mathbf{X})$ for all the k classes
- Practical difficulty: require initial knowledge of many probabilities, significant computational cost

Towards Naïve Bayesian Classifier

- Let D be a training set of tuples and their associated class labels, and each tuple is represented by an n -D attribute vector $\mathbf{X} = (x_1, x_2, \dots, x_n)$
- Suppose there are m classes C_1, C_2, \dots, C_m .
- Classification is to derive the maximum posteriori, i.e., the maximal $P(C_i|\mathbf{X})$
- This can be derived from Bayes' theorem

$$P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}$$

- Since $P(\mathbf{X})$ is constant for all classes, only

$$P(C_i|\mathbf{X}) = P(\mathbf{X}|C_i)P(C_i)$$

needs to be maximized

Derivation of Naïve Bayes Classifier

- A simplified assumption: attributes are conditionally independent (i.e., no dependence relation between attributes):

$$P(\mathbf{X} | C_i) = \prod_{k=1}^n P(x_k | C_i) = P(x_1 | C_i) \times P(x_2 | C_i) \times \dots \times P(x_n | C_i)$$

- This greatly reduces the computation cost: Only counts the class distribution
- If A_k is categorical, $P(x_k | C_i)$ is the # of tuples in C_i having value x_k for A_k divided by $|C_i, D|$ (# of tuples of C_i in D)
- If A_k is continuous-valued, $P(x_k | C_i)$ is usually computed based on Gaussian distribution with a mean μ and standard deviation σ

$$g(x, \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

and $P(x_k | C_i)$ is

$$P(\mathbf{X} | C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i})$$

Naïve Bayesian Classifier: Training Dataset

age	income	student	credit_rating	comp
<=30	high	no	fair	no
<=30	high	no	excellent	no
31...40	high	no	fair	yes
>40	medium	no	fair	yes
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31...40	high	yes	fair	yes
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Class:

C1:buys_computer = 'yes'

C2:buys_computer = 'no'

Data sample

X = (age <=30,

Income = medium,

Student = yes

Credit_rating = Fair)

Naïve Bayesian Classifier: An Example

- $P(C_i)$:
 $P(\text{buys_computer} = \text{"yes"}) = 9/14 = 0.643$
 $P(\text{buys_computer} = \text{"no"}) = 5/14 = 0.357$
- Compute $P(X|C_i)$ for each class
 $P(\text{age} = \text{"<=30"} | \text{buys_computer} = \text{"yes"}) = 2/9 = 0.222$
 $P(\text{age} = \text{"<= 30"} | \text{buys_computer} = \text{"no"}) = 3/5 = 0.6$
 $P(\text{income} = \text{"medium"} | \text{buys_computer} = \text{"yes"}) = 4/9 = 0.444$
 $P(\text{income} = \text{"medium"} | \text{buys_computer} = \text{"no"}) = 2/5 = 0.4$
 $P(\text{student} = \text{"yes"} | \text{buys_computer} = \text{"yes"}) = 6/9 = 0.667$
 $P(\text{student} = \text{"yes"} | \text{buys_computer} = \text{"no"}) = 1/5 = 0.2$
 $P(\text{credit_rating} = \text{"fair"} | \text{buys_computer} = \text{"yes"}) = 6/9 = 0.667$
 $P(\text{credit_rating} = \text{"fair"} | \text{buys_computer} = \text{"no"}) = 2/5 = 0.4$
- **$X = (\text{age} \leq 30, \text{income} = \text{medium}, \text{student} = \text{yes}, \text{credit_rating} = \text{fair})$**

$$P(X|C_i) : P(X|\text{buys_computer} = \text{"yes"}) = 0.222 \times 0.444 \times 0.667 \times 0.667 = 0.044$$

$$P(X|\text{buys_computer} = \text{"no"}) = 0.6 \times 0.4 \times 0.2 \times 0.4 = 0.019$$

$$P(X|C_i) * P(C_i) : P(X|\text{buys_computer} = \text{"yes"}) * P(\text{buys_computer} = \text{"yes"}) = 0.028$$

$$P(X|\text{buys_computer} = \text{"no"}) * P(\text{buys_computer} = \text{"no"}) = 0.007$$

Therefore, X belongs to class ("buys_computer = yes")

Avoiding the 0-Probability Problem

- Naïve Bayesian prediction requires each conditional prob. be non-zero. Otherwise, the predicted prob. will be zero

$$P(X | C_i) = \prod_{k=1}^n P(x_k | C_i)$$

- Ex. Suppose a dataset with 1000 tuples, income=low (0), income=medium (990), and income = high (10),
- Use Laplacian correction (or Laplacian estimator)
 - Adding 1 to each case
 - Prob(income = low) = 1/1003
 - Prob(income = medium) = 991/1003
 - Prob(income = high) = 11/1003
 - The “corrected” prob. estimates are close to their “uncorrected” counterparts

Naïve Bayesian Classifier: Comments

- Advantages
 - Easy to implement
 - Good results obtained in most of the cases
- Disadvantages
 - Assumption: class conditional independence, therefore loss of accuracy
 - Practically, dependencies exist among variables
 - E.g., hospitals: patients: Profile: age, family history, etc.
Symptoms: fever, cough etc., Disease: lung cancer, diabetes, etc.
 - Dependencies among these cannot be modeled by Naïve Bayesian Classifier
- How to deal with these dependencies?
 - Bayesian Belief Networks

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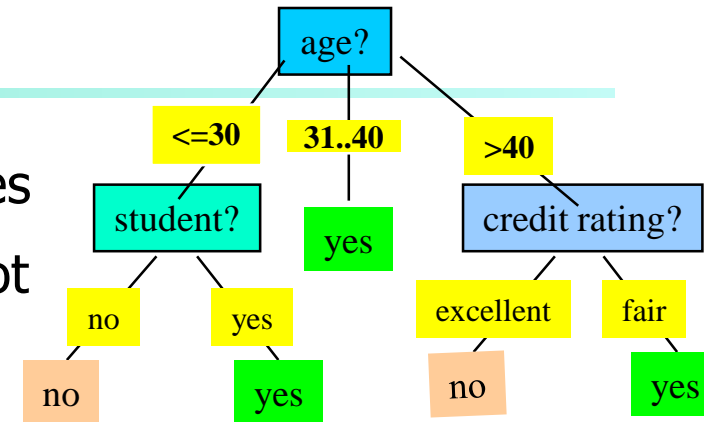


Using IF-THEN Rules for Classification

- Represent the knowledge in the form of **IF-THEN** rules
 - R: IF *age* = youth AND *student* = yes THEN *buys_computer* = yes
 - Rule antecedent/precondition vs. rule consequent
- Assessment of a rule: *coverage* and *accuracy*
 - n_{covers} = # of tuples covered by R
 - n_{correct} = # of tuples correctly classified by R
 - coverage(R) = $n_{\text{covers}} / |D|$ /* D: training data set */
 - accuracy(R) = $n_{\text{correct}} / n_{\text{covers}}$
- If more than one rule is triggered, need **conflict resolution**
 - Size ordering: assign the highest priority to the triggering rules that has the “toughest” requirement (i.e., with the *most attribute test*)
 - Class-based ordering: decreasing order of *prevalence or misclassification cost per class*
 - Rule-based ordering (**decision list**): rules are organized into one long priority list, according to some measure of rule quality or by experts

Rule Extraction from a Decision Tree

- Rules are easier to understand than large trees
- One rule is created for each path from the root to a leaf
- Each attribute-value pair along a path forms a conjunction: the leaf holds the class prediction
- Rules are mutually exclusive and exhaustive
- Example: Rule extraction from our *buys_computer* decision-tree



IF *age* = young AND *student* = *no* THEN *buys_computer* = *no*

IF *age* = young AND *student* = *yes* THEN *buys_computer* = *yes*

IF *age* = mid-age THEN *buys_computer* = *yes*

IF *age* = old AND *credit_rating* = *excellent* THEN *buys_computer* = **no**

IF *age* = **old** AND *credit_rating* = *fair* THEN *buys_computer* = **yes**

Rule Extraction from the Training Data

- Sequential covering algorithm: Extracts rules directly from training data
- Typical sequential covering algorithms: FOIL, AQ, CN2, RIPPER
- Rules are learned *sequentially*, each for a given class C_i will cover many tuples of C_i but none (or few) of the tuples of other classes
- Steps:
 - Rules are learned one at a time
 - Each time a rule is learned, the tuples covered by the rules are removed
 - The process repeats on the remaining tuples unless *termination condition*, e.g., when no more training examples or when the quality of a rule returned is below a user-specified threshold
- Comp. w. decision-tree induction: learning a set of rules *simultaneously*

How to Learn-One-Rule?

- Start with the most general rule possible: condition = empty
- Adding new attributes by adopting a greedy depth-first strategy
 - Picks the one that most improves the rule quality
- Rule-Quality measures: consider both coverage and accuracy
 - Foil-gain (in FOIL & RIPPER): assesses info_gain by extending condition

$$FOIL_Gain = pos' \times \left(\log_2 \frac{pos'}{pos'+neg'} - \log_2 \frac{pos}{pos+neg} \right)$$

It favors rules that have high accuracy and cover many positive tuples

- Rule pruning based on an independent set of test tuples

$$FOIL_Prune(R) = \frac{pos - neg}{pos + neg}$$

Pos/neg are # of positive/negative tuples covered by R.

If *FOIL_Prune* is higher for the pruned version of R, prune R

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Associative Classification

- Associative classification
 - Association rules are generated and analyzed for use in classification
 - Search for strong associations between frequent patterns (conjunctions of attribute-value pairs) and class labels
 - Classification: Based on evaluating a set of rules in the form of
$$P_1 \wedge p_2 \dots \wedge p_l \rightarrow "A_{\text{class}} = C" (\text{conf}, \text{sup})$$
- Why effective?
 - It explores highly confident associations among multiple attributes and may overcome some constraints introduced by decision-tree induction, which considers only one attribute at a time
 - In many studies, associative classification has been found to be more accurate than some traditional classification methods, such as C4.5

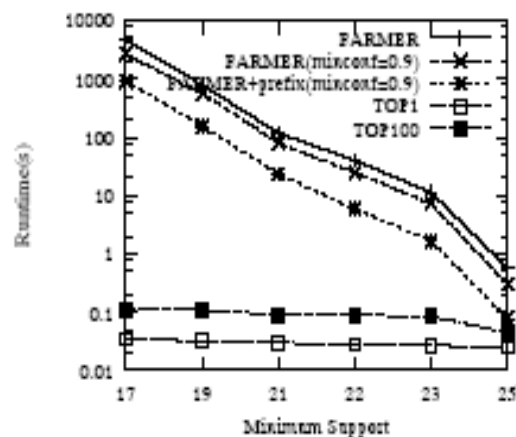
Typical Associative Classification Methods

- CBA (Classification By Association: Liu, Hsu & Ma, KDD'98)
 - Mine association possible rules in the form of
 - Cond-set (a set of attribute-value pairs) → class label
 - Build classifier: Organize rules according to decreasing precedence based on confidence and then support
- CMAR (Classification based on Multiple Association Rules: Li, Han, Pei, ICDM'01)
 - Classification: Statistical analysis on multiple rules
- CPAR (Classification based on Predictive Association Rules: Yin & Han, SDM'03)
 - Generation of predictive rules (FOIL-like analysis)
 - High efficiency, accuracy similar to CMAR
- RCBT (Mining top- k covering rule groups for gene expression data, Cong et al. SIGMOD'05)
 - Explore high-dimensional classification, using top- k rule groups
 - Achieve high classification accuracy and high run-time efficiency

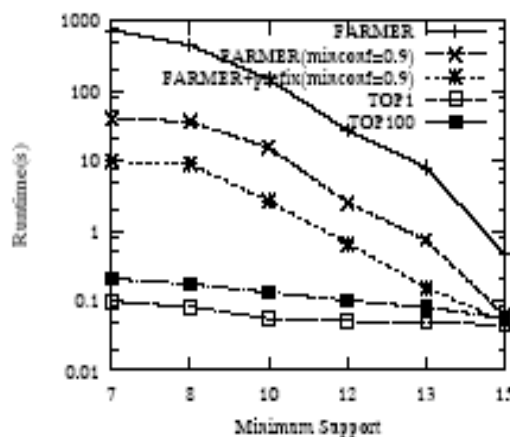
Associative Classification May Achieve High Accuracy and Efficiency (Cong et al. SIGMOD05)

Dataset	RCBT	CBA	IRG Classifier	C4.5 family			SVM
				single tree	bagging	boosting	
AML/ALL (ALL)	91.18%	91.18%	64.71%	91.18%	91.18%	91.18%	97.06%
Lung Cancer(LC)	97.99%	81.88%	89.93%	81.88%	96.64%	81.88%	96.64%
Ovarian Cancer(OC)	97.67%	93.02%	-	97.67%	97.67%	97.67%	97.67%
Prostate Cancer(PC)	97.06%	82.35%	88.24%	26.47%	26.47%	26.47%	79.41%
Average Accuracy	95.98%	87.11%	80.96%	74.3%	77.99%	74.3%	92.70%

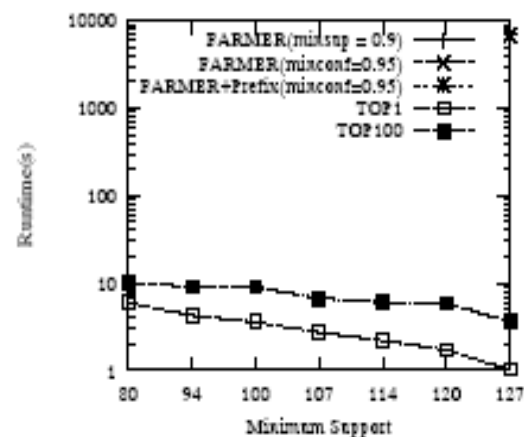
Table 2: Classification Results



(a) ALL-AML leukemia




(b) Lung Cancer



(c) Ovarian Cancer

Chapter 4. Classification and Prediction

- What is classification? What is prediction?
- Issues regarding classification and prediction
- Classification by decision tree induction
- Bayesian classification
- Rule-based classification
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- Lazy learners (or learning from your neighbors) 
- Other classification methods
- Prediction
- Summary

Lazy vs. Eager Learning

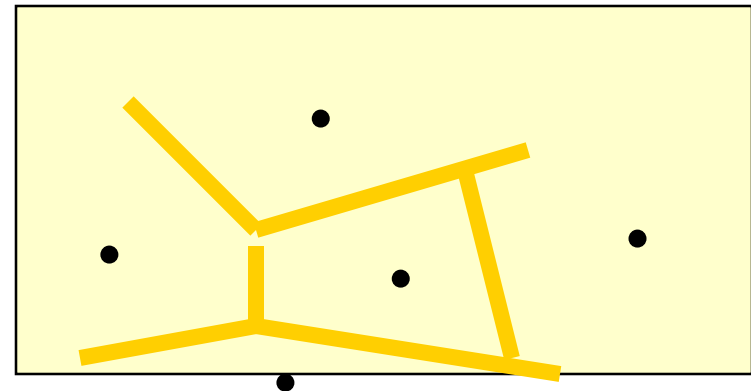
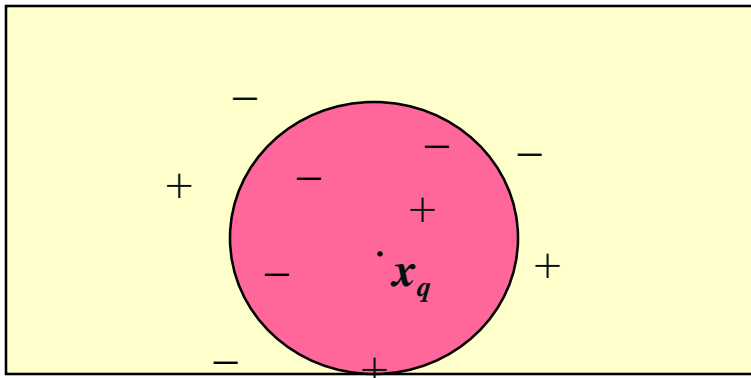
- Lazy vs. eager learning
 - Lazy learning (e.g., instance-based learning): Simply stores training data (or only minor processing) and waits until it is given a test tuple
 - Eager learning (the above discussed methods): Given a set of training set, constructs a classification model before receiving new (e.g., test) data to classify
- Lazy: less time in training but more time in predicting
- Accuracy
 - Lazy method effectively uses a richer hypothesis space since it uses many local linear functions to form its implicit global approximation to the target function
 - Eager: must commit to a single hypothesis that covers the entire instance space

Lazy Learner: Instance-Based Methods

- Instance-based learning:
 - Store training examples and delay the processing (“lazy evaluation”) until a new instance must be classified
- Typical approaches
 - k -nearest neighbor approach
 - Instances represented as points in a Euclidean space.
 - Locally weighted regression
 - Constructs local approximation
 - Case-based reasoning
 - Uses symbolic representations and knowledge-based inference

The k -Nearest Neighbor Algorithm

- All instances correspond to points in the n-D space
- The nearest neighbor are defined in terms of Euclidean distance, $\text{dist}(\mathbf{X}_1, \mathbf{X}_2)$
- Target function could be discrete- or real- valued
- For discrete-valued, k -NN returns the most common value among the k training examples nearest to x_q
- Voronoi diagram: the decision surface induced by 1-NN for a typical set of training examples




Discussion on the k -NN Algorithm

- k -NN for real-valued prediction for a given unknown tuple
 - Returns the mean values of the k nearest neighbors
- Distance-weighted nearest neighbor algorithm
 - Weight the contribution of each of the k neighbors according to their distance to the query x_q
 - Give greater weight to closer neighbors $w \equiv \frac{1}{d(x_q, x_i)^2}$
- Robust to noisy data by averaging k -nearest neighbors
- Curse of dimensionality: distance between neighbors could be dominated by irrelevant attributes
 - To overcome it, axes stretch or elimination of the least relevant attributes

Case-Based Reasoning (CBR)

- CBR: Uses a database of problem solutions to solve new problems
- Store symbolic description (tuples or cases)—not points in a Euclidean space
- Applications: Customer-service (product-related diagnosis), legal ruling
- Methodology
 - Instances represented by rich symbolic descriptions (e.g., function graphs)
 - Search for similar cases, multiple retrieved cases may be combined
 - Tight coupling between case retrieval, knowledge-based reasoning, and problem solving
- Challenges
 - Find a good similarity metric
 - Indexing based on syntactic similarity measure, and when failure, backtracking, and adapting to additional cases


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Genetic Algorithms (GA)

- Genetic Algorithm: based on an analogy to biological evolution
- An initial **population** is created consisting of randomly generated rules
 - Each rule is represented by a string of bits
 - E.g., if A_1 and $\neg A_2$ then C_2 can be encoded as 100
 - If an attribute has $k > 2$ values, k bits can be used
- Based on the notion of survival of the **fittest**, a new population is formed to consist of the fittest rules and their offsprings
- The fitness of a rule is represented by its *classification accuracy* on a set of training examples
- Offsprings are generated by *crossover* and *mutation*
- The process continues until a population P evolves *when each rule in P satisfies a prespecified threshold*
- Slow but easily parallelizable

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What Is Prediction?

- (Numerical) prediction is similar to classification
 - construct a model
 - use model to predict continuous or ordered value for a given input
- Prediction is different from classification
 - Classification refers to predict categorical class label
 - Prediction models continuous-valued functions
- Major method for prediction: regression
 - model the relationship between one or more *independent* or **predictor** variables and a *dependent* or **response** variable
- Regression analysis
 - Linear and multiple regression
 - Non-linear regression
 - Other regression methods: generalized linear model, Poisson regression, log-linear models, regression trees

Linear Regression

- Linear regression: involves a response variable y and a single predictor variable x

$$y = w_0 + w_1 x$$

where w_0 (y-intercept) and w_1 (slope) are regression coefficients

- Method of least squares: estimates the best-fitting straight line

$$w_1 = \frac{\sum_{i=1}^{|D|} (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^{|D|} (x_i - \bar{x})^2} \quad w_0 = \bar{y} - w_1 \bar{x}$$

- Multiple linear regression: involves more than one predictor variable
 - Training data is of the form $(\mathbf{X}_1, y_1), (\mathbf{X}_2, y_2), \dots, (\mathbf{X}_{|D|}, y_{|D|})$
 - Ex. For 2-D data, we may have: $y = w_0 + w_1 x_1 + w_2 x_2$
 - Solvable by extension of least square method or using SAS, S-Plus
 - Many nonlinear functions can be transformed into the above

Nonlinear Regression

- Some nonlinear models can be modeled by a polynomial function
- A polynomial regression model can be transformed into linear regression model. For example,

$$y = w_0 + w_1 x + w_2 x^2 + w_3 x^3$$

convertible to linear with new variables: $x_2 = x^2$, $x_3 = x^3$


$$y = w_0 + w_1 x + w_2 x_2 + w_3 x_3$$

- Other functions, such as power function, can also be transformed to linear model
- Some models are intractable nonlinear (e.g., sum of exponential terms)
 - possible to obtain least square estimates through extensive calculation on more complex formulae

Other Regression-Based Models

- Generalized linear model:
 - Foundation on which linear regression can be applied to modeling categorical response variables
 - Variance of y is a function of the mean value of y , not a constant
 - Logistic regression: models the prob. of some event occurring as a linear function of a set of predictor variables
 - Poisson regression: models the data that exhibit a Poisson distribution
- Log-linear models: (for categorical data)
 - Approximate discrete multidimensional prob. distributions
 - Also useful for data compression and smoothing
- Regression trees and model trees
 - Trees to predict continuous values rather than class labels

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Summary (I)

- **Classification** and **prediction** are two forms of data analysis that can be used to extract **models** describing important data classes or to predict future data trends.
- Effective and scalable methods have been developed for **decision trees induction, Naive Bayesian classification, rule-based classifier, associative classification, nearest neighbor classifiers, and case-based reasoning**, and other classification methods such as **genetic algorithms**.
- **Linear, nonlinear, and generalized linear models of regression** can be used for **prediction**. Many nonlinear problems can be converted to linear problems by performing transformations on the predictor variables.

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